

The Unified Transform for a Class of Reaction-Diffusion Problems with Discontinuous Time Dependent Parameters

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Abstract—Reaction-diffusion mathematical models for studying, among others, highly diffusive brain tumors, that also take into account the heterogeneity of the brain tissue, are frequently used in recent years. Current work, considers a generalized class of such reaction-diffusion models that also allows both diffusion and reaction parameters to depend continuously in time. A series of transforms are applied to produce an integral representation of the problem's solution. Main approach used is Fokas unified transform which yields novel integral representations of the solution in the complex plane that, for appropriately chosen integration contours, decay exponentially fast and converge uniformly at the boundaries. Combining these method-inherent advantages with numerical integration techniques on hyperbolic contours, we produce an efficient method, with fast decaying error properties, for the solution of the multi-domain reaction-diffusion model problem.

Index Terms—Reaction-Diffusion PDEs, Brain tumors, Unified transform, Fokas method.

I. INTRODUCTION

Reaction-diffusion linear PDEs have been the core biomathematical model for studying highly invasive and aggressive forms of brain tumors for many years now (e.g. [10], [7] and the references therein). The driving differential equation of the basic model has the form

$$\frac{\partial \bar{c}}{\partial \bar{t}} = \nabla \cdot (\bar{D} \nabla \bar{c}) + \bar{\rho} \bar{c}, \quad (1)$$

where $\bar{c}(\bar{x}, \bar{t})$ denotes the tumor cell density at location \bar{x} and time \bar{t} , $\bar{\rho}$ denotes the net proliferation rate (0.012 1/day, cf. [2]), and \bar{D} is the diffusion coefficient representing the active motility of malignant cells (0.0013 cm^2/day , cf. [16]). The model also considers zero flux boundary conditions, which impose no migration of cells beyond the brain boundaries, and an initial condition $\bar{c}(\bar{x}, 0) = \bar{f}(\bar{x})$, where $\bar{f}(\bar{x})$ is the initial spatial distribution of malignant cells.

Predicting a linear growth of the mean tumor diameter on MRI, Swanson (cf. [14], [15]) incorporated brain's tissue heterogeneity (white-gray matter) into the basic model by considering \bar{D} be defined by

$$\bar{D} \equiv \bar{D}(\bar{x}) = \begin{cases} \bar{D}_w, & \bar{x} \text{ in white matter } (\bar{x} \in \bar{\Omega}_w) \\ \bar{D}_g, & \bar{x} \text{ in gray matter } (\bar{x} \in \bar{\Omega}_g) \end{cases}, \quad (2)$$

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where \bar{D}_w and \bar{D}_g are scalars with $\bar{D}_w > \bar{D}_g$.

The above important model problem may be considered as part of a more general class of problems characterized by the fact that both diffusion and reaction parameters depend also in time. To be more specific, we'll assume that

$$\bar{D}(\bar{x}, \bar{t}) = \bar{\chi}(\bar{t}) \bar{D}(\bar{x}) \quad \text{and} \quad \bar{\rho} \equiv \bar{\rho}(\bar{t}), \quad (3)$$

where $\bar{\chi}(\bar{t}) \neq 0$ and $\bar{\rho}(\bar{t}) \neq 0$ are continuous functions of \bar{t} . In such a case, models that would, for example, allow both motility and proliferation of malignant cells to change in time are also included.

Assuming, for compatibility purposes, the same physical units and using the dimensionless variables (see also [14], [15] for an analogous treatment)

$$t = \bar{\rho}_0 \bar{t}, \quad x = \sqrt{\frac{\bar{\rho}_0}{\bar{\chi}_0 \bar{D}_w}} \bar{x}, \quad \chi(t) = \frac{\bar{\chi}(\bar{\rho}_0 \bar{t})}{\bar{\chi}_0}, \quad \gamma = \frac{\bar{D}_g}{\bar{D}_w}, \quad (4)$$

hence

$$D \equiv D(x) = \begin{cases} 1, & x \in \Omega_w \\ \gamma, & x \in \Omega_g \end{cases}, \quad D(x, t) = \chi(t) D(x), \quad (5)$$

$$\rho \equiv \rho(t) = \frac{1}{\bar{\rho}_0} \bar{\rho}(\bar{\rho}_0 \bar{t}), \quad f(x) = \bar{f} \left(\sqrt{\frac{\bar{\rho}_0}{\bar{\chi}_0 \bar{D}_w}} x \right), \quad (6)$$

and

$$c(x, t) = \frac{\bar{\chi}_0 \bar{D}_w}{\bar{\rho}_0 N_0} \bar{c} \left(\sqrt{\frac{\bar{\rho}_0}{\bar{\chi}_0 \bar{D}_w}} x, \bar{\rho}_0 \bar{t} \right), \quad (7)$$

with $N_0 = \int \bar{f}(\bar{x}) d\bar{x}$ to denote the initial number of tumor cells in the brain at $\bar{t}_0 = 0$, $\bar{\rho}_0 = \bar{\rho}(\bar{t}_0)$ and $\bar{\chi}_0 = \bar{\chi}(\bar{t}_0)$, one may easily arrive at the dimensionless equation

$$\frac{\partial}{\partial t} c(x, t) = \nabla \cdot (D(x, t) \nabla c(x, t)) + \rho(t) c(x, t). \quad (8)$$

Referring, now, to the above equation we proceed in the next sections as follows:

- Initially, by using appropriate transformations and change of variables, we reduce the above equation into an equivalent one with constant diffusion coefficient.
- In the sequel, for the one space dimension problem and by using the Fokas unified transform method (cf. [3], [4]), we produce an integral representation of the solution in the complex plane that, for an appropriately chosen integration contour, decay exponentially fast.
- Finally, we apply efficient numerical integration techniques, with fast decaying error properties, for the numerical evaluation of the solution's integral representation.

We remark that our work here extends and completes the works in [9] and [1].

II. INTEGRAL REPRESENTATION OF THE SOLUTION

A. Equivalence Transformations

Let us first show that:

Lemma 1. If $c(x, t)$ satisfies equation (8) and $u(x, t)$ is defined by

$$u(x, t) = e^{-R(t)} c(x, t) \text{ with } R(t) = \int_0^t \rho(s) ds, \quad (9)$$

then $u(x, t)$ satisfies the equation

$$\frac{\partial}{\partial t} u(x, t) = \nabla \cdot (D(x, t) \nabla u(x, t)) . \quad (10)$$

Proof: Observing that $\dot{R}(t) = \rho(t)$ and differentiating (9) with respect of t , it can be easily shown that

$$e^{-R(t)} \frac{\partial}{\partial t} c(x, t) = \frac{\partial}{\partial t} u(x, t) + \rho(t) u(x, t) . \quad (11)$$

Multiplication now of equation (8) by the factor $e^{-R(t)}$ yields

$$e^{-R(t)} \frac{\partial}{\partial t} c(x, t) = \nabla \cdot (D(x, t) \nabla u(x, t)) + \rho(t) u(x, t) , \quad (12)$$

which combined with relation (11) completes the proof. ■

Recalling, now, the form of $D(x, t)$ form (5), we can easily show that:

Lemma 2. If $u(x, t)$ satisfies Lemma 1 and

$$\tau \equiv \tau(t) = \int_0^t \chi(s) ds , \quad (13)$$

then $u(x, \tau)$ satisfies the equation

$$\frac{\partial}{\partial \tau} u(x, \tau) = \nabla \cdot (D(x) \nabla u(x, \tau)) . \quad (14)$$

Proof: Upon writing $D(x, t) = \chi(t) D(x)$ equation (10) of Lemma 1 becomes

$$\frac{\partial}{\partial t} u(x, t) = \chi(t) \nabla \cdot (D(x) \nabla u(x, t)) . \quad (15)$$

Apparently, now, the fact that

$$\frac{\partial}{\partial t} u(x, t) = \frac{d\tau}{dt} \frac{\partial}{\partial \tau} u(x, \tau) = \chi(t) \frac{\partial}{\partial \tau} u(x, \tau) , \quad (16)$$

completes the proof. ■

B. The unified transform for the 1 + 1 problem

In view of Lemmas 1 and 2, the dimensionless IBVP problem in 1+1 dimensions may be written as

$$\begin{cases} u_\tau = (Du_x)_x, & x \in [a, b], \quad \tau > 0 \\ u_x(a, \tau) = 0 \text{ and } u_x(b, \tau) = 0 \\ u(x, 0) = f(x) := \sum_{i=1}^M \delta(x - \xi_i), & \xi_i \in (a, b) \end{cases} , \quad (17)$$

where D and τ are as defined in (5) and (13), respectively, and $\delta(x)$ denotes the Dirac delta function.

Due to brain tissue heterogeneity, the domain $[a, b]$ is considered partitioned into $n + 1$ regions $R_j := (w_{j-1}, w_j)$, with $a \equiv w_0 < w_1 < w_2 < \dots < w_n < w_{n+1} \equiv b$, and if, for some j , R_j is white matter region, then R_{j-1} and R_{j+1} are grey matter regions. Thus, for $x \in R_j$, $j = 1, \dots, n+1$, we denote the dimensionless diffusion coefficient $D(x)$ as

$$D(x) = \gamma_j = \begin{cases} 1, & \text{when } R_j \subseteq \Omega_w \\ \gamma, & \text{when } R_j \subseteq \Omega_g \end{cases} . \quad (18)$$

Furthermore, notice that the parabolic nature of the problem directly implies continuity of both u and Du_x across each interface point w_j . Hence, for each $j = 1, 2, \dots, n$ we have

$$u(w_j, \tau) := \lim_{x \rightarrow w_j^+} u(x, \tau) = \lim_{x \rightarrow w_j^-} u(x, \tau) \quad (19)$$

$$Du_x(w_j, \tau) := \lim_{x \rightarrow w_j^+} D(x) u_x(x, \tau) = \lim_{x \rightarrow w_j^-} D(x) u_x(x, \tau) . \quad (20)$$

Let, now, $u^{(j)}(x, \tau)$ denote the solution of the multi-domain problem defined over $\bar{R}_j := \{w_{j-1}\} \cup R_j \cup \{w_j\} = [w_{j-1}, w_j]$. Namely, for $j = 1, \dots, n + 1$,

$$u^{(j)}(x, \tau) := \begin{cases} u(x, \tau), & x \in R_j \\ \lim_{x \rightarrow w_{j-1}^+} u(x, \tau), & x = w_{j-1} \\ \lim_{x \rightarrow w_j^-} u(x, \tau), & x = w_j \end{cases} , \quad (21)$$

and, naturally,

$$\begin{cases} u_x^{(j)}(w_{j-1}, \tau) := \lim_{x \rightarrow w_{j-1}^+} u_x(x, \tau) \\ u_x^{(j)}(w_j, \tau) := \lim_{x \rightarrow w_j^-} u_x(x, \tau) \end{cases} . \quad (22)$$

Apparently then,

$$u_\tau^{(j)} = (\gamma_j u_x^{(j)})_x = \gamma_j u_{xx}^{(j)} , \quad (23)$$

while, recalling the constrains (19)-(20), there also holds:

$$\begin{cases} u^{(j)}(w_j, \tau) = u^{(j+1)}(w_j, \tau) \\ \gamma_j u_x^{(j)}(w_j, \tau) = \gamma_{j+1} u_x^{(j+1)}(w_j, \tau) \end{cases} . \quad (24)$$

Observe, now, that the formal adjoint $\tilde{u}^{(j)}$ satisfies the equation

$$-\tilde{u}_\tau^{(j)} = \gamma_j \tilde{u}_{xx}^{(j)} . \quad (25)$$

Then, by multiplying equations (23) and (25) by $\tilde{u}^{(j)}$ and $u^{(j)}$, respectively, and subtracting the resulting equations, we obtain that

$$(u^{(j)} \tilde{u}^{(j)})_\tau - (\gamma_j u_x^{(j)} \tilde{u}^{(j)} - \gamma_j u^{(j)} \tilde{u}_x^{(j)})_x = 0 . \quad (26)$$

Taking, also, into consideration that a one-parameter family of solutions of (25) is given by

$$\tilde{u}^{(j)}(x, \tau; k) = e^{-ikx + \gamma_j k^2 \tau}, \quad k \in \mathbb{C} \quad (27)$$

equation (26) becomes

$$(e^{-ikx + \gamma_j k^2 \tau} u^{(j)})_\tau - (e^{-ikx + \gamma_j k^2 \tau} \gamma_j (u_x^{(j)} + ik u^{(j)}))_x = 0 \quad (28)$$

which is the *divergence form* of equation (23). Integrating, now, over the region $A_j := \{(x, \tau) : x \in \bar{R}_j, 0 \leq \tau \leq T\}$ and using Green's Theorem we obtain that:

$$\begin{aligned} & \int_{w_{j-1}}^{w_j} e^{-ikx} f^{(j)}(x) dx - \int_{w_{j-1}}^{w_j} e^{-ikx + \gamma_j k^2 T} u^{(j)}(x, T) dx \\ & - \int_0^T e^{-ikw_{j-1} + \gamma_j k^2 \tau} \gamma_j [u_x^{(j)}(w_{j-1}, \tau) + ik u^{(j)}(w_{j-1}, \tau)] d\tau \\ & + \int_0^T e^{-ikw_j + \gamma_j k^2 \tau} \gamma_j [u_x^{(j)}(w_j, \tau) + ik u^{(j)}(w_j, \tau)] d\tau = 0 , \end{aligned} \quad (29)$$

where $f^{(j)}(x)$ is the initial condition restrained in region $\overline{R_j}$, namely

$$f^{(j)}(x) = f(x)|_{\overline{R_j}} .$$

Let $\widehat{f}^{(j)}(x)$ and $\widehat{u}^{(j)}(k, \tau)$ denote the (windowed) Fourier transforms of functions $f^{(j)}(x)$ and $u^{(j)}(x, \tau)$, respectively, that is

$$\widehat{f}^{(j)}(k) = \int_{w_{j-1}}^{w_j} e^{-ikx} f^{(j)}(x) dx \quad (30)$$

and

$$\widehat{u}^{(j)}(k, \tau) = \int_{w_{j-1}}^{w_j} e^{-ikx} u^{(j)}(x, \tau) dx . \quad (31)$$

Furthermore, let the functions $\widetilde{u}^{(j)}$ and $\widetilde{u}_x^{(j)}$ defined by

$$\widetilde{u}^{(j)}(x, \gamma_j k^2) := \int_0^T e^{\gamma_j k^2 \tau} u^{(j)}(x, \tau) d\tau \quad (32)$$

and

$$\widetilde{u}_x^{(j)}(x, \gamma_j k^2) := \int_0^T e^{\gamma_j k^2 \tau} u_x^{(j)}(x, \tau) d\tau . \quad (33)$$

Then, equation (29) becomes

$$\begin{aligned} e^{\gamma_j k^2 T} \widehat{u}^{(j)}(k, T) &= \widehat{f}^{(j)}(k) - \\ &- \gamma_j e^{-ikw_{j-1}} [\widetilde{u}_x^{(j)}(w_{j-1}, \gamma_j k^2) + ik\widetilde{u}^{(j)}(w_{j-1}, \gamma_j k^2)] + \\ &+ \gamma_j e^{-ikw_j} [\widetilde{u}_x^{(j)}(w_j, \gamma_j k^2) + ik\widetilde{u}^{(j)}(w_j, \gamma_j k^2)] , \end{aligned} \quad (34)$$

for all $k \in \mathbb{C}$. Moreover, by noticing that the above equation is valid for all $\tau \in [0, T]$, even when $T \rightarrow \infty$, replacement of T by τ in (34) leads to the global relation

$$\begin{aligned} e^{\gamma_j k^2 \tau} \widehat{u}^{(j)}(k, \tau) &= \widehat{f}^{(j)}(k) - \\ &- \gamma_j e^{-ikw_{j-1}} [\widetilde{u}_x^{(j)}(w_{j-1}, \gamma_j k^2) + ik\widetilde{u}^{(j)}(w_{j-1}, \gamma_j k^2)] + \\ &+ \gamma_j e^{-ikw_j} [\widetilde{u}_x^{(j)}(w_j, \gamma_j k^2) + ik\widetilde{u}^{(j)}(w_j, \gamma_j k^2)] , \end{aligned} \quad (35)$$

for all $k \in \mathbb{C}$. Letting, now, $\lambda_j^2 = \gamma_j k^2$ and $c_j = \gamma_j^{-\frac{1}{2}}$, and relabel, in the sequel, λ to k , the final form of the global relation relation is given by

$$\begin{aligned} e^{k^2 \tau} \widehat{u}^{(j)}(c_j k, \tau) &= \widehat{f}^{(j)}(c_j k) - \\ &- \gamma_j e^{-ic_j k w_{j-1}} [\widetilde{u}_x^{(j)}(w_{j-1}, k^2) + ic_j k \widetilde{u}^{(j)}(w_{j-1}, k^2)] + \\ &+ \gamma_j e^{-ic_j k w_j} [\widetilde{u}_x^{(j)}(w_j, k^2) + ic_j k \widetilde{u}^{(j)}(w_j, k^2)] , \end{aligned} \quad (36)$$

for all $k \in \mathbb{C}$.

Finally, inverting the Fourier transform $\widehat{u}^{(j)}(c_j k, \tau)$ in equation (36), we obtain the integral form of the solution $u^{(j)}(x, \tau)$ as

$$\begin{aligned} u^{(j)}(x, \tau) &= \frac{c_j}{2\pi} \int_{-\infty}^{+\infty} e^{ic_j k x - k^2 \tau} \widehat{f}^{(j)}(c_j k) dk \\ &- \frac{1}{2\pi c_j} \int_{-\infty}^{+\infty} e^{ic_j k (x - w_{j-1}) - k^2 \tau} \\ &\cdot [\widetilde{u}_x^{(j)}(w_{j-1}, k^2) + ic_j k \widetilde{u}^{(j)}(w_{j-1}, k^2)] dk \quad (37) \\ &+ \frac{1}{2\pi c_j} \int_{-\infty}^{+\infty} e^{ic_j k (x - w_j) - k^2 \tau} \\ &\cdot [\widetilde{u}_x^{(j)}(w_j, k^2) + ic_j k \widetilde{u}^{(j)}(w_j, k^2)] dk , \end{aligned}$$

for $j = 1, 2, \dots, n+1$, and by applying the constrains (24) as well as the Neumann boundary conditions

$$\begin{aligned} u^{(1)}(x, \tau) &= \frac{c_1}{2\pi} \int_{-\infty}^{+\infty} e^{ic_1 k x - k^2 \tau} \widehat{f}^{(1)}(c_1 k) dk \\ &- \frac{1}{2\pi} \int_{-\infty}^{+\infty} ik e^{ic_1 k (x-a) - k^2 \tau} \widetilde{u}^{(1)}(a, k^2) dk \\ &+ \frac{1}{2\pi c_1} \int_{-\infty}^{+\infty} e^{ic_1 k (x - w_1) - k^2 \tau} \\ &\cdot [\widetilde{u}_x^{(1)}(w_1, k^2) + ic_1 k \widetilde{u}^{(1)}(w_1, k^2)] dk , \end{aligned} \quad (38)$$

$$\begin{aligned} u^{(j)}(x, \tau) &= \frac{c_j}{2\pi} \int_{-\infty}^{+\infty} e^{ic_j k x - k^2 \tau} \widehat{f}^{(j)}(c_j k) dk \\ &- \frac{1}{2\pi c_j} \int_{-\infty}^{+\infty} e^{ic_j k (x - w_{j-1}) - k^2 \tau} \\ &\cdot [\frac{\gamma_j^{j-1}}{\gamma_j} \widetilde{u}_x^{(j-1)}(w_{j-1}, k^2) + ic_j k \widetilde{u}^{(j-1)}(w_{j-1}, k^2)] dk \\ &+ \frac{1}{2\pi c_j} \int_{-\infty}^{+\infty} e^{ic_j k (x - w_j) - k^2 \tau} \\ &\cdot [\widetilde{u}_x^{(j)}(w_j, k^2) + ic_j k \widetilde{u}^{(j)}(w_j, k^2)] dk , \end{aligned} \quad (39)$$

for $j = 2, 3, \dots, n$,

$$\begin{aligned} u^{(n+1)}(x, \tau) &= \frac{c_{n+1}}{2\pi} \int_{-\infty}^{+\infty} e^{ic_{n+1} k x - k^2 \tau} \widehat{f}^{(n+1)}(c_{n+1} k) dk \\ &- \frac{1}{2\pi c_{n+1}} \int_{-\infty}^{+\infty} e^{ic_{n+1} k (x - w_n) - k^2 \tau} \\ &\cdot [\frac{\gamma_n}{\gamma_{n+1}} \widetilde{u}_x^{(n)}(w_n, k^2) + ic_{n+1} k \widetilde{u}^{(n)}(w_n, k^2)] dk \\ &+ \frac{1}{2\pi} \int_{-\infty}^{+\infty} ik e^{ic_{n+1} k (x-b) - k^2 \tau} \widetilde{u}^{(n+1)}(b, k^2) dk . \end{aligned} \quad (40)$$

For the evaluation of the $2n+2$ unknown quantities

- $\widetilde{u}^{(1)}(a, k^2)$ and $\widetilde{u}^{(n+1)}(b, k^2)$
- $\widetilde{u}^{(j)}(w_j, k^2)$ and $\widetilde{u}_x^{(j)}(w_j, k^2)$ for $j = 1, 2, \dots, n$

in the above expressions (38) - (40), we use the transform $k \rightarrow -k$ in equation (35) to obtain

$$\begin{aligned} e^{k^2 \tau} \widehat{u}^{(j)}(-c_j k, \tau) &= \widehat{f}^{(j)}(-c_j k) - \\ &- \gamma_j e^{ic_j k w_{j-1}} [\widetilde{u}_x^{(j)}(w_{j-1}, k^2) - ic_j k \widetilde{u}^{(j)}(w_{j-1}, k^2)] + \\ &+ \gamma_j e^{ic_j k w_j} [\widetilde{u}_x^{(j)}(w_j, k^2) - ic_j k \widetilde{u}^{(j)}(w_j, k^2)] , \end{aligned} \quad (41)$$

for all $k \in \mathbb{C}$. This equation is combined with the global relation in (36), as well as the constrains (24) and the boundary conditions, to produce the equations:

- for $j = 1$:

$$\begin{aligned} ic_1 \gamma_1 k e^{-ic_1 k a} \widetilde{u}^{(1)}(a, k^2) - ic_1 \gamma_1 k e^{-ic_1 k w_1} \widetilde{u}^{(1)}(w_1, k^2) + \\ + \gamma_1 e^{-ic_1 k w_1} \widetilde{u}_x^{(1)}(w_1, k^2) = \widehat{f}(c_1 k) , \end{aligned} \quad (42)$$

$$\begin{aligned}
 & -ic_1\gamma_1ke^{ic_1kw_0}\tilde{u}^{(1)}(w_0, k^2) + ic_1\gamma_1ke^{ic_1kw_1}\tilde{u}^{(1)}(w_1, k^2) - \\
 & -\gamma_1e^{-ic_1kw_1}\tilde{u}_x^{(1)}(w_1, k^2) = \hat{f}(-c_1k),
 \end{aligned} \tag{43}$$

• for $j = 2, 3, \dots, n$:

$$\begin{aligned}
 & ic_j\gamma_jke^{-ic_jkw_{j-1}}\tilde{u}^{(j-1)}(w_{j-1}, k^2) + \\
 & + \gamma_{j-1}e^{-ic_jkw_{j-1}}\tilde{u}_x^{(j-1)}(w_{j-1}, k^2) - \\
 & - ic_j\gamma_jke^{-ic_jkw_j}\tilde{u}^{(j)}(w_j, k^2) - \\
 & - \gamma_je^{-ic_jkw_j}\tilde{u}_x^{(j)}(w_j, k^2) = \hat{f}(c_jk),
 \end{aligned} \tag{44}$$

$$\begin{aligned}
 & -ic_j\gamma_jke^{ic_jkw_{j-1}}\tilde{u}^{(j-1)}(w_{j-1}, k^2) + \\
 & + \gamma_{j-1}e^{ic_jkw_{j-1}}\tilde{u}_x^{(j-1)}(w_{j-1}, k^2) + \\
 & + ic_j\gamma_jke^{ic_jkw_j}\tilde{u}^{(j)}(w_j, k^2) - \\
 & - \gamma_je^{ic_jkw_j}\tilde{u}_x^{(j)}(w_j, k^2) = \hat{f}(-c_jk),
 \end{aligned} \tag{45}$$

• for $j = n + 1$:

$$\begin{aligned}
 & ic_{n+1}\gamma_{n+1}ke^{-ic_{n+1}kw_n}\tilde{u}^{(n)}(w_n, k^2) + \\
 & + \gamma_n e^{-ic_{n+1}kw_n}\tilde{u}_x^{(n)}(w_n, k^2) - \\
 & - ic_{n+1}\gamma_{n+1}ke^{-ic_{n+1}kb}\tilde{u}^{(n+1)}(b, k^2) = \hat{f}(c_{n+1}k),
 \end{aligned} \tag{46}$$

$$\begin{aligned}
 & -ic_{n+1}\gamma_{n+1}ke^{ic_{n+1}kw_n}\tilde{u}^{(n)}(w_n, k^2) + \\
 & + \gamma_n e^{ic_{n+1}kw_n}\tilde{u}_x^{(n)}(w_n, k^2) + \\
 & + ic_{n+1}\gamma_{n+1}ke^{ic_{n+1}kb}\tilde{u}^{(n+1)}(b, k^2) = \hat{f}(-c_{n+1}k).
 \end{aligned} \tag{47}$$

The above $2n + 2$ equations form the complex linear system

$$\mathbf{G}\tilde{\mathbf{u}} = \hat{\mathbf{f}}, \tag{48}$$

where the nonzero elements of the matrix $G = \{G_{p,q}\}$ are defined by:

• for $j = 1$:

$$\begin{bmatrix} G_{1,1} & G_{1,2} & G_{1,3} \\ G_{2,1} & G_{2,2} & G_{2,3} \end{bmatrix} = \begin{bmatrix} A_1^{(1)} & A_3^{(1)} & A_4^{(1)} \\ A_5^{(1)} & A_7^{(1)} & A_8^{(1)} \end{bmatrix} \tag{49}$$

• for $j = 2, 3, \dots, n$:

$$\begin{aligned}
 & \begin{bmatrix} G_{2j-1,2j-2} & G_{2j-1,2j-1} & G_{2j-1,2j} & G_{2j-1,2j+1} \\ G_{2j,2j-2} & G_{2j,2j-1} & G_{2j,2j} & G_{2j,2j+1} \end{bmatrix} = \\
 & = \begin{bmatrix} A_1^{(j)} & A_2^{(j)} & A_3^{(j)} & A_4^{(j)} \\ A_5^{(j)} & A_6^{(j)} & A_7^{(j)} & A_8^{(j)} \end{bmatrix}
 \end{aligned} \tag{50}$$

• for $j = n + 1$:

$$\begin{aligned}
 & \begin{bmatrix} G_{2n+1,2n} & G_{2n+1,2n+1} & G_{2n+1,2n+2} \\ G_{2n+2,2n} & G_{2n+2,2n+1} & G_{2n+2,2n+2} \end{bmatrix} = \\
 & = \begin{bmatrix} A_1^{(n+1)} & A_2^{(n+1)} & A_3^{(n+1)} \\ A_5^{(n+1)} & A_6^{(n+1)} & A_7^{(n+1)} \end{bmatrix}
 \end{aligned} \tag{51}$$

with

m	$A_m^{(j)}$	$A_{m+1}^{(j)}$
1	$ic_j\gamma_jke^{-ic_jkw_{j-1}}$	$\gamma_{j-1}e^{-ic_jkw_{j-1}}$
3	$-ic_j\gamma_jke^{-ic_jkw_j}$	$-\gamma_je^{-ic_jkw_j}$
5	$-ic_j\gamma_jke^{ic_jkw_{j-1}}$	$\gamma_{j-1}e^{ic_jkw_{j-1}}$
7	$ic_j\gamma_jke^{ic_jkw_j}$	$-\gamma_je^{ic_jkw_j}$

and

$$\tilde{\mathbf{u}} = \begin{bmatrix} \tilde{u}^{(1)}(a, k^2) \\ \tilde{u}^{(1)}(w_1, k^2) \\ \tilde{u}_x^{(1)}(w_1, k^2) \\ \vdots \\ \tilde{u}^{(n)}(w_n, k^2) \\ \tilde{u}_x^{(n)}(w_n, k^2) \\ \tilde{u}^{(n+1)}(b, k^2) \end{bmatrix}, \quad \hat{\mathbf{f}} = \begin{bmatrix} \hat{f}^{(1)}(c_1k) \\ \hat{f}^{(1)}(-c_1k) \\ \vdots \\ \hat{f}^{(n+1)}(c_{n+1}k) \\ \hat{f}^{(n+1)}(-c_{n+1}k) \end{bmatrix}.$$

Observe that terms involving the Fourier transforms $\tilde{u}^{(j)}(\pm c_jk, \tau)$ have been omitted from relations (42)-(47) and the system (48) as the quantities $\frac{\tilde{u}^{(j)}(\pm c_jk, \tau)}{\det(G)}$ are negligible (cf. [13]).

Solving, now, the above linear system we can determine the unknown quantities required in evaluating (38)-(40).

C. Integration Contours and Integral Properties

The analyticity of the functions involved in the integral representation of $u^{(j)}(x, \tau)$ in (37), allows the replacement of the real axis $(-\infty, \infty)$ by other contours of integration in the complex plane. For this, let

$$\begin{aligned}
 \Gamma &= \{k \in \mathbb{C} : \text{Re}(\gamma_jk^2) < 0\} \\
 &= \{k \in \mathbb{C} : \text{arg}(k) \in (\frac{\pi}{4}, \frac{3\pi}{4}) \cup (\frac{5\pi}{4}, \frac{7\pi}{4})\}
 \end{aligned}$$

and

$$\begin{aligned}
 \Gamma^+ &= \Gamma \cap \mathbb{C}^+, & \mathbb{C}^+ &= \{k \in \mathbb{C} : \text{Im}(k) > 0\}, \\
 \Gamma^- &= \Gamma \cap \mathbb{C}^-, & \mathbb{C}^- &= \{k \in \mathbb{C} : \text{Im}(k) < 0\}.
 \end{aligned}$$

Then, it can be easily verified, that:

- $e^{ic_jk(x-w_{j-1})}$ ($x - w_{j-1} > 0$) is bounded and analytic for $\text{Im}(k) > 0$
- $e^{ic_jk(x-w_j)}$ ($x - w_j < 0$) is bounded and analytic for $\text{Im}(k) < 0$
- $e^{-k^2\tau}$ ($t \geq 0$) is bounded and analytic for $\text{Re}(k^2) \geq 0$.

Therefore, by using Cauchy's Theorem and Jordan's Lemma, the representation of $u^{(j)}(x, \tau)$ in (37) can be equivalently expressed as

$$\begin{aligned}
 u^{(j)}(x, \tau) &= \frac{c_j}{2\pi} \int_{-\infty}^{+\infty} e^{ic_jkx - k^2\tau} \hat{f}^{(j)}(c_jk) dk \\
 &- \frac{1}{2\pi c_j} \int_{\partial\Gamma^+} e^{ic_jk(x-w_{j-1}) - k^2\tau} \\
 &\cdot [\tilde{u}_x^{(j)}(w_{j-1}, k^2) + ic_jk\tilde{u}^{(j)}(w_{j-1}, k^2)] dk \\
 &- \frac{1}{2\pi c_j} \int_{\partial\Gamma^-} e^{ic_jk(x-w_j) - k^2\tau} \\
 &\cdot [\tilde{u}_x^{(j)}(w_j, k^2) + ic_jk\tilde{u}^{(j)}(w_j, k^2)] dk.
 \end{aligned} \tag{52}$$

It is known (cf. [17], [18]) that one approach to the numerical quadrature of the above integrals is to apply the trapezoid rule on suitable hyperbolic contours (see also [5], [12]). For this, we map the points θ on the real line to the points $\pm k(\theta)$ of the complex plane by using the analytic function:

$$k_\theta \equiv k(\theta) := i \sin(\beta - i\theta). \tag{53}$$

Evidently the $k(\theta)$ and $-k(\theta)$ curves, as shown in Figure 1 replace the integration paths $\partial\Gamma^+$ and $\partial\Gamma^-$ respectively.

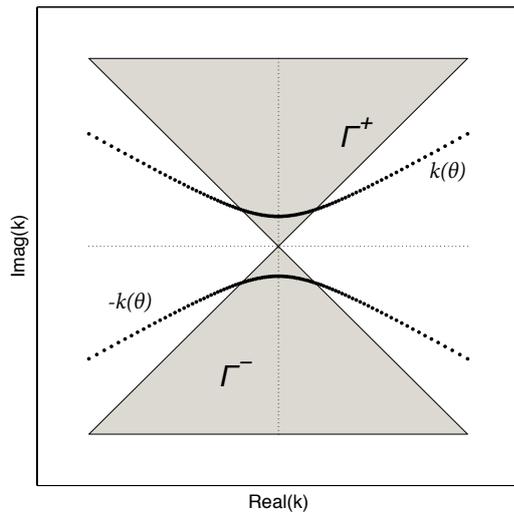


Fig. 1: The contours $\pm k(\theta)$ for numerical integration

Using the above parametrization, the solution (52) is written as

$$\begin{aligned}
 u^{(j)}(x, \tau) = & \frac{c_j}{2\pi} \int_{-\infty}^{+\infty} e^{ic_j kx - k^2 \tau} \widehat{f}^{(j)}(c_j k) dk \\
 & - \frac{1}{2\pi c_j} \int_{-\infty}^{+\infty} e^{ic_j k_\theta(x-w_{j-1}) - k_\theta^2 \tau} \\
 & \cdot [\widetilde{u}_x^{(j)}(w_{j-1}, k_\theta^2) + ic_j k_\theta \widetilde{u}^{(j)}(w_{j-1}, k_\theta^2)] k'_\theta dk_\theta \\
 & - \frac{1}{2\pi c_j} \int_{-\infty}^{+\infty} e^{-ic_j k_\theta(x-w_j) - k_\theta^2 \tau} \\
 & \cdot [\widetilde{u}_x^{(j)}(w_j, k_\theta^2) - ic_j k_\theta \widetilde{u}^{(j)}(w_j, k_\theta^2)] k'_\theta dk_\theta, \quad (54)
 \end{aligned}$$

for all $j = 1, 2, \dots, n + 1$, with k'_θ to denote the derivative of $k(\theta)$, namely

$$k'_\theta = \cos(\beta - i\theta). \quad (55)$$

We point out that the corresponding to (38)-(40) integral representations of the solution can be easily derived by applying the constrains (24) as well as the Neumann boundary conditions.

D. Evaluation of the Integrals

The first integral in equation (54) can be evaluated analytically (see also [9]) since the $f^{(j)}$ is a sum of Dirac's delta functions. To be more specific, observe that

$$f^{(j)}(x) = \sum_{i=1}^M \delta(x - \xi_i), \text{ for all } \xi_i \in (w_{j-1}, w_j) \quad (56)$$

hence

$$\widehat{f}^{(j)}(c_j k) = \sum_{i=1}^M e^{-ic_j k \xi_i}, \text{ for all } \xi_i \in (w_{j-1}, w_j) \quad (57)$$

and therefore the first integral term in (54)

$$\frac{c_j}{2\pi} \int_{-\infty}^{\infty} e^{ic_j kx} e^{-k^2 \tau} \widehat{f}^{(j)}(c_j k) dk = \frac{c_j}{2\sqrt{t\pi}} \sum_{i=1}^M e^{-\frac{c_j^2 (\xi_i - x)^2}{4t}}. \quad (58)$$

The last two integrals in equation (54) have to be evaluated numerically. For the efficient implementation of numerical quadrature rules, one has to take into consideration the following basic algebraic properties:

- The real parts of all integrands are *even* functions of θ .
- The imaginary parts of all integrands are *odd* functions of θ .
- The integrands are decaying functions of θ .

The proof of the first two properties follows after a few algebraic manipulations (cf. [11]) while the third one is a direct consequence of the selected integration paths. Application of the above properties directly implies that

$$\int_{-\infty}^{\infty} U(\theta) d\theta = 2 \int_0^{\infty} \text{Re}(U(\theta)) d\theta \approx 2 \int_0^{\Theta} \text{Re}(U(\theta)) d\theta,$$

where $U(\theta)$ denotes any one of the last two integrands involved in (54) and Θ is a relatively *small* real number. For a good estimate of Θ one may require the dominant exponential term $e^{-k_\theta^2 \tau}$, common in all integrals, to satisfy

$$|e^{-k_\theta^2 \tau}| \leq 10^{-M} \text{ for all } \theta \geq \Theta \equiv \Theta(\tau; M)$$

for sufficiently large M , hence (cf. [9])

$$\Theta = \frac{1}{2} \ln \frac{4\tau + 8M \ln 10}{\tau}. \quad (59)$$

NUMERICAL SOLUTION

Following ([5], [12]) and our work in [9], to numerically evaluate the integrals in relation (54) above, we apply the trapezoid rule using the parametrization (53). For the asymptotes of the hyperbola with $\beta = \pi/6$, as in [9].

For the numerical experiments we have used $[a, b] = [-5, 5]$ for the interval endpoints and

$$[w_1, w_2, w_3, w_4, w_5] = [-3, -2, -1, 0, 3]$$

for the interior interfaces. Cell motility and proliferation, in this artificial example, are using $\chi(t) = 0.2t$, $\gamma_j = \gamma = D_g/D_w = 0.2$ for all $j = 1, 3, 5$ and $\rho = 1$.

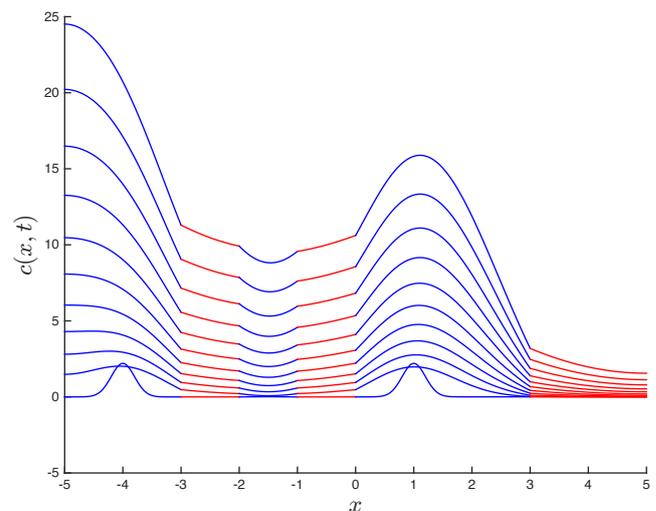


Fig. 2: Time evolution of cell density $c(x, t)$ for the case of two initial sources.

In Figure 2, the time evolution of cells for the case of two initial sources of cells, centered at $\xi_1 = -4$ and

$\xi_2 = 1$, is depicted for various time levels $t = t_m$ ($m = 0, 1, \dots$). Hence, each curve on the figure represents the cell density at a specific time level, namely $c(x, t_m)$. In complete analogy, in Figures 3 we depict the case of one initial source of cells centered, obviously, at $\xi_1 = 1$.

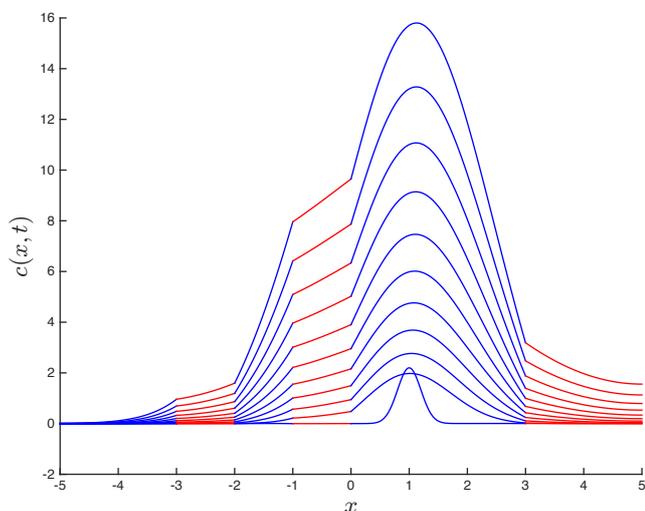


Fig. 3: Time evolution of cell density $c(x, t)$ for the case of one initial source.

Observe that, in both cases, the solution is continuous on the whole interval and smooth everywhere except at the interface points, as expected. We point out that, for the evaluation of each $c(x, t_m)$ curve no information at different time levels is used.

The relative error is given by

$$E_N := \|u_{N_{i+1}} - u_{N_i}\|_\infty / \|u_{N_{i+1}}\|_\infty,$$

where N denotes the number of quadrature points, and u_N is the corresponding numerical solution. From Figure 4 we observe the rapidly decaying convergence rate of E_N .

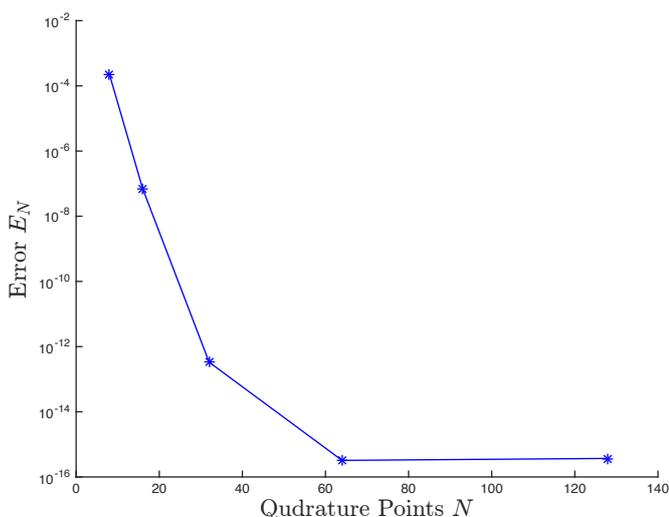


Fig. 4: The relative error E_N

CONCLUSION

The Fokas transform method, combined with numerical integration on hyperbolic contours, is applied to the solution

of a multi-domain brain tumor invasion problem, modeled by a reaction-diffusion linear equation with time dependent coefficients and a discontinuous diffusion to characterize brain's tissue heterogeneity. The exact solution is produced in integral form at any space-time point and evaluated by a fast convergent quadrature.

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